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may not always be possible because of the requirements of other components of the device to arrange this. In that case, the table may be moved between the capture zones of each of apparatus 10A, 10B, 10C and position signals from the incremental detector indicating the movement of the table between specific positions as indicated by the reference detection apparatus 10A, 10B, 10C used to determine the zero reference position. Output signals OS from the position detecting apparatus 10A, 10B, 10C and the interferometers IF are combined by a combiner CB to determine an absolute position of the table.

See the attached Appendix for the changes made to effect the above paragraph

IN THE CLAIMS:

Please amend claim 19 as follows:

(Amended) Apparatus according to claim 18, wherein the three position 19. detection devices are arranged orthogonally with respect to each other.

See the attached Appendix for the changes made to effect the above claim.